Imprints of Dirac Structure in Emergent Gravity and a geometric T-dual avatar

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Quantum Gravity in the Southern Cone VII March 31, 2017

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Emergent Gravity

- Review and Two Important Theorems
- Geometry of Emergent Gravity

2 Geometrical T-duality

• A plausible T-dual avatar

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Emergent Gravity Lightning Review

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- Consider a line bundle L over (M, B) whose connection 1-form is denoted by A = A_μ(x)dx^μ. The curvature F of a line bundle is a closed two-form, i.e., dF = 0 and so locally can be expressed as F = dA. The line bundle L over (M, B) admits a local gauge symmetry 𝔅_L which acts on A as well as on the symplectic structure B on the base manifold M :

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• The local gauge symmetry \mathfrak{B}_L demands the curvature F = dA of L to appear only as the combination $\mathcal{F} \equiv B + F$ since the two-form \mathcal{F} is gauge invariant under the Λ -symmetry. Since $d\mathcal{F} = 0$, the line bundle L over (M, B) leads to a "dynamical" symplectic manifold (M, \mathcal{F}) if $det(1 + F\theta) \neq 0$ where $\theta \equiv B^{-1}$.

Emergent Gravity

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- Let us conceive an analogue in general relativity. In GR, the gravitational force gives rise to the deformation of a given Euclidean space (M, g), which results in a "dynamical" Riemannian manifold (\mathcal{M}, G) where G = g + h. The equivalence principle then suggests that the "dynamical" Riemannian manifold (\mathcal{M}, G) can always be trivialized in a locally inertial frame where the metric G goes to the original unperturbed one g.

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- The electromagnetic force is to the deformation of a symplectic manifold what the gravitational force is to the deformation of a Riemannian manifold. The emergent gravity picture implies that these two deformations are isomorphic to each other.

B field transformation : yet another diffeomorphism!!

Theorem

Since B is a symplectic structure on M, it defines a bundle isomorphism $B: TM \to T^*M$ by $X \mapsto \Lambda = -\iota_X B$ where $X \in \Gamma(TM)$ is an arbitrary vector field. As a result, the B-field transformation can be written as

$$\mathfrak{B}_L: (B,A) \mapsto (B + \mathcal{L}_X B, A - \iota_X B)$$

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Example

U(1) gauge symmetry, $A \mapsto A + d\lambda$, is a particular case of the Λ -symmetry for $\Lambda = d\lambda = -\iota_{X_{\lambda}}B$. $X_{\lambda} = -\theta(d\lambda)$ is called a Hamiltonian vector field. Since a vector field is an infinitesimal generator of local coordinate transformations, or, a Lie algebra generator of Diff(M), the B-field transformation can be identified with a local coordinate transformation generated by the vector field $X \in \Gamma(TM)$. Hence Λ -symmetry can be considered on par with diffeomorphism. In the presence of B-fields, there is an enhancement of the underlying local gauge symmetry.

Darboux Theorem in Emergent Gravity

The situation is similar to GR where the dynamical symplectic manifold (M, F) can be locally trivialized by a coordinate transformation φ ∈ Diff(M) such that φ^{*}(F) = φ^{*}(B + F) = B. diffeomorphism, φ^{*} = (1 + L_X)⁻¹ ≈ e^{-L_X} for A = −Λ = ι_XB.

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- In other words, it is always possible to find a local coordinate transformation eliminating dynamical U(1) gauge fields as far as the spacetime admits a symplectic structure. This statement is known as the Darboux theorem or the Moser lemma in symplectic geometry which is the crux of emergent gravity.

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Theorem

Let (M, ω) be a 2n- dimensional symplectic manifold. For each point $x \in M$, there is a local chart (U, ϕ) where U is an open neigborhood of x, and $\phi : U \to \mathbb{R}^{2n}$ is a diffeomorphism such that $\phi^*(\sum_{i=1}^n dx_i \wedge dy_i) = \omega_{|U|}$

Lemma

Let M be a compact manifold with symplectic forms ω_0 and ω_1 . Suppose that ω_t , $0 \le t \le 1$, is a smooth family of symplectic forms joining ω_0 to ω_1 with cohomology class $[\omega_t]$ independent of t. Then there exists an isotopy $\rho : M \times \mathbb{R} \to M$ such that $\rho_t^* \omega_t = \omega_0$, $0 \le t \le 1$.

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Example

There always exists a coordinate transformation ϕ whose pullback maps $\omega' = \omega_1 = \omega + dA$ to ω , i.e., $\phi : y \mapsto x = x(y)$ is such that

$$\frac{\partial x^{\alpha}}{\partial y^{a}}\frac{\partial x^{\beta}}{\partial y^{b}}\omega_{\alpha\beta}'(x)=\omega_{ab}(y).$$

For a symplectic manifold $(M, \omega_1 = B + F)$ one can always find a local coordinate chart $(U; y^1, \dots, y^{2n})$ centered at $p \in M$ and valid in the nghbd U s.t. $\omega_0(p) = \frac{1}{2}B_{ab}dy^a \wedge dy^b$, B_{ab} is a const symplectic matrix.

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 The group of orthogonal Courant automorphisms of TM ⊕ T*M is a semi-direct product of Diff(M) and Ω²_{closed}, i.e. Diff(M) κ Ω²_{closed}.

Diffeomorphism between two different metrics

• Courant Action :
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- In terms of local coordinates $(g + \kappa B')_{\alpha\beta}(x) = \frac{\partial y^{a}}{\partial x^{\alpha}} \left(h_{ab}(y) + \kappa B_{ab}(y) \right) \frac{\partial y^{b}}{\partial x^{\beta}} \text{ where } B' = B + \mathcal{L}_{X}B$ and $\partial x^{\alpha} \partial x^{\beta}$

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$$h_{ab}(y) = \frac{\partial x^{\alpha}}{\partial y^{a}} \frac{\partial x^{\beta}}{\partial y^{b}} g_{\alpha\beta}(x)$$

• Local equivalence between symplectic structures \rightsquigarrow diffeomorphic equivalence between two different DBI metrics (Cornalba)

$$\int d^{p+1}x \sqrt{\det(g(x) + \kappa(B+F)(x))} = \int d^{p+1}y \sqrt{\det(h(y) + \kappa B(y))}$$

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Bilinear non-degenerate pairing

Let E and F be linear spaces of dims. m and n respectively, endowed with a bilinear non-degenerate pairing (,) : $E \times F \to \mathbb{R}$, and consider the total space $(F \times E, \langle, \rangle_+)$. Let E be a linear space (of dim m), $F = E^*$ and let (,) be the duality pairing of E and E^* . Suppose M is a smooth oriented (compact) *m*-manifold, $F = \Lambda^k(M)$, i. e. the space of all k-forms, on M and $E = \Lambda^{m-k}(M)$. Now consider the nondegenerate bilinear pairing $(,): \Lambda^k(M) \times \Lambda^{m-k}(M) \to \mathbb{R}, \ (\alpha, \beta) = \int_M (\beta \wedge \alpha) \ \forall \alpha, \beta \text{ s.t. } \alpha \in \Lambda^k(M)$ and $\beta \in \Lambda^{m-k}(M)$. Poincare duality theorem \Rightarrow we effectively identify the dual of F with E. The next step is to associate to (,), the non-degenerate symmetric, bilinear pairing $\langle, \rangle_+ \ \forall (f^1, e^1), (f^2, e^2) \in F \times E.$ $\left\langle \left(f^{1}, e^{1}\right), \left(f^{2}, e^{2}\right)\right\rangle_{\perp} = \frac{1}{2}\left[\left(f^{1}, e^{2}\right) + \left(f^{2}, e^{1}\right)\right]$

Dirac Structure continued.

Theorem

Let F and E be linear spaces, and let (,) : $F \times E \to \mathbb{R}$ be a non-degenerate bilinear pairing and consider a subspace $\mathcal{D} \subset (F \times E, \langle, \rangle_+)$. The orthogonal complement of \mathcal{D} , denoted by \mathcal{D}^{\perp} , wrt \langle, \rangle_+ , is given by: $\mathcal{D}^{\perp} = \left\{ \left(\bar{f}, \bar{e} \right) \in F \times E \left| \left\langle (f, e), \left(\bar{f}, \bar{e} \right) \right\rangle_+ = 0, \forall (s, \alpha) \in \mathcal{D} \right\}.$

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Theorem

Let F and E be linear spaces (of finite dims), endowed with a bilinear nondegenerate pairing (,) and consider the total space ($F \times E, \langle, \rangle_+$). The linear subspace $\mathcal{D} \subset (F \times E, \langle, \rangle_+)$ is a DS if $\mathcal{D} = \mathcal{D}^{\perp}$.

Theorem

Let F and E be linear spaces, and let (,) : $F \times E \to \mathbb{R}$ be a non-degenerate bilinear pairing and consider a subspace $\mathcal{D} \subset (F \times E, \langle, \rangle_+)$. The orthogonal complement of \mathcal{D} , denoted by \mathcal{D}^{\perp} , wrt \langle, \rangle_+ , is given by: $\mathcal{D}^{\perp} = \left\{ \left(\bar{f}, \bar{e} \right) \in F \times E \left| \left\langle (f, e), \left(\bar{f}, \bar{e} \right) \right\rangle_+ = 0, \forall (s, \alpha) \in \mathcal{D} \right\}.$

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Example

Let E be a linear space of dim m, and let E^* be the algebraic dual of E and consider the linear maps $A : E \to E^*$ and $B : E^* \to E$ respectively. The maps A and B are skew-symmetric maps if and only if their graphs, are DS.

Dirac Manifold

Theorem

Let *M* be a finite dim. smooth manifold. We define symmetric and skew-symmetric operations on the vector bundle $\mathbb{T}^{big}M := TM \oplus T^*M$ over *M* as $\langle X \oplus \xi, Y \oplus \eta \rangle_+ := \frac{1}{2} \{\xi(Y) + \eta(X)\} \in \mathbb{C}^{\infty}(M)$ and $[X \oplus \xi, Y \oplus \eta]_C := [X, Y] \oplus (\mathcal{L}_X \eta - i_Y d\xi) \in \Gamma^{\infty}(M, \mathbb{T}^{big}M)$ $\forall X \oplus \xi, Y \oplus \eta \in \Gamma^{\infty}(M, \mathbb{T}^{big}M)$. A subbundle $\mathcal{D} \subset \mathbb{T}^{big}M$ is called a Dirac structure on *M* if

1 $\langle \cdot, \cdot \rangle_+|_{\mathcal{D}} \equiv 0;$

2 \mathcal{D} has rank equal to dimM;

M together with DS $\mathcal{D} \subset \mathbb{T}^{big} M$ is called a Dirac manifold, denoted by (M, \mathcal{D}) . In addition to the natural pairing $\langle \cdot, \cdot \rangle_+$, skew-symmetric pairing can be defined. $\langle X \oplus \xi, Y \oplus \eta \rangle_- := \frac{1}{2} \{\xi(Y) - \eta(X)\} \in \mathbb{C}^{\infty}(M)$. The orthogonal complement of a subbundle $\mathcal{D} \subset (\mathbb{T}^{big}, \langle, \rangle_+)$, is $\mathcal{D}^{\perp} = (Y, \eta) \in \mathbb{T}^{big} M | \langle (X, \xi), (Y, \eta) \rangle_+ = 0, \forall (X, \xi) \in \mathcal{D}$

Dirac Manifold in Emergent Gravity

Theorem

Let *M* be a smooth *m*-manifold and let $\mathbb{T}^{big}M$ be the big tangent bundle of *M*. The subbundle $\mathcal{D} \subset (\mathbb{T}^{big}M, \langle, \rangle_+)$ is a Dirac structure if $\mathcal{D} = \mathcal{D}^{\perp}$

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Example

Suppose that M is a symplectic manifold with a symplectic form ω . that induces the bundle map ω^{\flat} : $\mathfrak{X}(M) \longrightarrow \Omega^{1}(M), \qquad X \longmapsto \iota_{X} \omega.$ One can obtain the subbundle graph (ω^{\flat}) in $\mathbb{T}^{big}M$ as $\operatorname{graph}(\omega^{\flat})_{p} := \{ X_{p} \oplus i_{X_{p}} \omega_{p} \in T_{p}M \oplus T_{p}^{*}M \,|\, X_{p} \in T_{p}M \} \quad (p \in M) \text{ and }$ can verify that the graph(ω^{\flat}) satisfies all the three conditions for $(M, \operatorname{graph}(\omega^{\flat}))$ to be a Dirac manifold. Similarly, any symplectic manifold M defines a Dirac structure on M. In emergent gravity, we have a closed *B*-field and e^B is an automorphism of the Courant bracket iff dB = 0, so naturally it induces a bundle isomorphism of this kind and hence (M, B) defines a Dirac manifold.

Emergent Gravity

- Review and Two Important Theorems
- Geometry of Emergent Gravity

2 Geometrical T-duality

• A plausible T-dual avatar

• In the low energy limit of type II strings, the bosonic field content are a metric g, closed 3-form H and dilaton φ that satisy modified Einstein equations. Surprisingly these set of eqns. possess a symmetry, namely T-duality that is not found in the ordinary Einstein eqns. and this symmetry relates spaces X, \hat{X} which are torus bundles over a common base space M and can be characterised by an interchange of Chern classes between the torus bundles with topological data associated to the closed 3-form H.

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- T-duality can be seen as an isomorphism between Courant algebroids E, Ê associated to the spaces X, X̂. Leaving aside the dilaton φ, the field content (g, H) defines a generalised metric on the Courant algebroid E. Then it is possible to understand the T-duality of the type II string equations as an isomorphism of generalised metrics.

• Use the argument of geometric T-duality that acts on the oriented circle bundles and exchange the first Chern class with the fiberwise integral of the *H*-flux. Construct a T-dual bundle over the same base.

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- Let us simplify the discussion by considering T-duality to act in one direction only, *i.e.* T-dualizing on a circle S¹, Consider E to be an oriented S¹-bundle over M characterized by its first Chern class c₁(E) ∈ H²(M, Z), in presence of non-trivial H-flux H ∈ H³(E, Z).

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- We argue that the T-dual of E is again an oriented S¹-bundle over M, denoted by Ê, supporting H-flux Ĥ ∈ H³(Ê, ℤ), such that c₁(Ê) = π_{*}H, c₁(E) = π̂_{*}Ĥ, where π_{*}: H^k(E,ℤ) → H^{k-1}(M,ℤ) and similarly π̂_{*}, are pushforward maps.

T-duality expression and Gysin Sequence

Duality

$$H = H_{(3)} + A \wedge H_{(2)}, \qquad \hat{H} = H_{(3)} + \hat{A} \wedge dA$$

with

$$F = dA$$
, $\hat{F} = d\hat{A} = H_{(2)}$

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The reason for the duality is understood in the following way, for an oriented S^k -bundle E, we've a long exact sequence in cohomology $\dots \to H^k(M,\mathbb{Z}) \xrightarrow{\pi^*} H^k(E,\mathbb{Z}) \xrightarrow{\pi_*} H^{k-1}(M,\mathbb{Z}) \xrightarrow{F\cup} H^{k+1}(M,\mathbb{Z}) \xrightarrow{\pi^*} \dots$.

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Example

Here is an example that deals with our scenario. Consider the k = 3 segment of this sequence.

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Proposal to construct $(E, H) \rightarrow (\hat{E}, \hat{H})$ _{k=3 segment of the sequence}

For any H-flux H ∈ H³(E, Z) we've an associated element Ê = π_{*}H ∈ H²(M, Z), and moreover, F ∪ Ê = 0 in H⁴(M, Z). Now, let Ê be the S¹-bundle associated to Ê. Reversing the roles of E and Ê in the Gysin sequence, we see that since F ∪ Ê = Ê ∪ F = 0, ∃ an Ĥ ∈ H³(Ê, Z) s.t. Â_{*}Ĥ = F, where Ĥ is unique up to an element of π^{*}H³(M, Z). The transformation (E, H) → (Ê, Ĥ), for a particular choice of Ĥ, is precisely what is T-duality for us.

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- The ambiguity in Ĥ, upto an element in π*H³(M, Z), is fixed by requiring that T-duality should act trivially on π*H³(M, Z), *i.e.* T-duality shouldn't affect H-flux which is completely supported on M.

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- Since H and Ĥ live on different spaces, in order to compare them we have to pull them back to the correspondence space, which in general is the fibered product E ×_M Ê = {(x, x̂) ∈ E × Ê | π(x) = π̂(x̂)}, which is both an Ŝ¹-bundle over E, as well as an S¹-bundle over Ê.

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 - Study the interplay between gerbes, topological T-duality and automorphisms of emergent gravity. (work in progress with Hull)

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